

- Optimization
 - standard form

$$p^* = \min_{x \in \mathbb{R}^n} f_0(x)$$

$$\text{subject to } f_i(x) \leq b_i, i=1, \dots, m$$
 - affine - linear constraint, equality
 - feasible set - satisfy constraints
 - suboptimal set = \mathcal{C} within \mathcal{P}^*
 - local sets
 - global set
 - equality reduction

$$h(x) = 0$$

$$h_1(x) = 0, h_2(x) \geq 0$$
 - ℓ_1 constraint - $x \in \mathbb{R}^n \setminus \{\text{axis } \ell_1\}$
 - max/min, $g_0(x) \geq g_1(x) - p^*$
 - infeasible - empty feasible set
 - feasibility problem $f(x) \leq c$ constant
 - optimal set - argmin $f(x)$
 - empty if infeasible
 - empty if optimal is a line
 - $\mathcal{C} \subset \mathbb{R}^n \times \text{boundary}$
 - local min - optimal within \mathcal{P}
 - focus on convex tractable problem
 - log transform $x_1, x_2 \mapsto \log x_1, \log x_2$
 - convex - local min = global min
 - Vectors
 - represent point, direction, linear function
 - scalar product - "angle"
 - column vector $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^n$
 - vector space - \mathcal{C}, \mathcal{X} comb.
 - subspace - closed under \mathcal{C} , scalar λ
 - span - all linear combinations of \mathcal{S} vectors
 - combination - $x \in \mathcal{C} \rightarrow \text{by linear form}$
 - linearity (hyperplane)

$$f(x) = a^T x + b = \text{distance}$$

$$\text{basis of } \mathcal{C} \rightarrow \text{span}(0, 1)^T$$
 - affine set - $\{x \in \mathbb{R}^n \mid a^T x + b \leq 0\} \cup \{x \in \mathbb{R}^n \mid a^T x + b > 0\}$
 - intersection of affine w/ origin (hyperplane)
 - line $L = \{x \in \mathbb{R}^n \mid a^T x + b = 0\}$
 - Euclidean length - $\|x\|_2$
 - norm

$$\|x\|_2 = 0, \|x\|_1 = 1.0, \|x\|_0 = 0$$
 - other

$$\|x\|_1 = \|x\|_2 + \|x\|_0 \quad (\text{triangle})$$

$$\|x\|_0 = \|x\|_1 \|x\|_2$$
 - epsilon norm $\|x\|_\epsilon = (\sum_i |x_i|^{\epsilon})^{1/\epsilon}$
 - $\|x\|_\infty = \sqrt[n]{\sum_i x_i^n}$ \rightarrow coordinate
 - $\|x\|_2 = \sqrt{x^T x}$ \rightarrow non-negative
 - $\|x\|_1 = \sum_i |x_i|$ \rightarrow non-zero
 - $\|x\|_0 = \max_i |x_i|$ \rightarrow non-zero
 - inner product $\langle x, y \rangle$
 - $\langle x, x \rangle = \|x\|_2^2$
 - $\langle x, y \rangle = \langle y, x \rangle$
 - $\langle x, y + z \rangle = \langle x, y \rangle + \langle x, z \rangle$
 - $\langle x, \alpha y \rangle = \alpha \langle x, y \rangle$
 - $\langle x, y \rangle = x^T y$
 - interpretation from comb
 - standard interpretation $\langle x, y \rangle = x^T y$
 - column norm $\|x\| = \sqrt{x^T x}$
 - angle

$$\cos \theta = \frac{x^T y}{\|x\| \|y\|_2}$$

$$x^T y = 0 \Rightarrow 90^\circ, \text{ orthogonal } x, y$$
 - Cauchy-Schwarz $|x^T y| \leq \|x\|_2 \|y\|_2$
 - Hadamard product

$$x \otimes y = \left(\frac{1}{n} \sum_i x_i y_i \right)^2$$

$$\|x \otimes y\|_2 \leq \sum_i |x_i y_i| \leq \|x\|_2 \|y\|_2$$
 - mutually orthogonal \rightarrow linearly independent
 - orthogonal decomposition

$$x = S \oplus L \perp P$$
 - Projection
 - point x known as ref point
 - proj H norm - unique proj x^H
 - $(x - x^H) \perp S$
 - point to line proj $x^L = v^T(p - x)v$
 - hyperplane $\|x - x^H\|_2^2$
 - hyperplane $p^H = \frac{a^T p - b}{\|a\|_2^2} a$
 - orthogonal proj $x^H = C_2^{-1} x^H$
 - Functions
 - $\mathbb{R}^{n_1} \times \mathbb{R}^{n_2} \rightarrow \mathbb{R}$
 - $f: \mathbb{R}^n \rightarrow \mathbb{R}$
 - graph $f = \{(x, f(x)) \in \mathbb{R}^{n+1} \times \mathbb{R} \mid x \in \mathbb{R}^n\}$
 - epif $f = \{(x, t) \in \mathbb{R}^{n+1} \times \mathbb{R} \mid t \geq f(x)\}$
 - $\text{conv}_t \text{func}_t = t$

- affinen $\text{Flan} = \mathbf{e}^T \mathbf{x} + b$
 - linear $\text{Flin} = \mathbf{c}^T \mathbf{x}$
 - Halbkreis $H = \mathbf{e}^T \mathbf{x} + b$
 $H_{\text{int}} = \mathbf{e}^T \mathbf{x} + b$
 - Gradient $\nabla \text{Flan} = \left[\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right]^T$
 $\text{Flan} = \text{Flin}_1 + \text{Flin}_2 + \dots + \text{Flin}_n$
 $\text{Flin}_i = \text{der Taylorapprox.}$
 \rightarrow In der Umgebung von x_0 kann man Flan schreiben
 - Matrix
 - linear map between spaces
 - $A \in \mathbb{C}^{m,n}$, m rows, n columns
 - $(A)_{ij}$ entries in elements
 - product $[AB]_{ij} = \sum_k A_{ik} B_{kj}$
 $\quad \quad \quad$ sum of row i and column j
 - $A_b = \sum_k a_{ik} b_k$
 - $c^T \Delta = \sum_k c_k \Delta_k^T$ or row k
 - $AB = \sum_{k=1}^n a_k b_k^T$ (row k)
 - $(AB)^T = B^T A^T$ (row k)
 - Range $R(A) = \{Ax \mid x \in \mathbb{R}^n\}$
 - Nullspace $N(A) = \{x \mid Ax = 0\}$
 - $R^{\perp} = N(A) \oplus R(A^T)$
 decomposition into orthogonal subspaces
 - Fundamental Theorem, Linear Algebra
 $R(A) = N(A^T)$
 - Determinant
 $\det(A) = \sum_{j=1}^n (-1)^{j+1} a_{1j} \det(A_{1j})$
 Bedingung für $\det A = 0$: $a_{1j} \neq 0$ und
 $a_{21} = a_{2j}^T A^T$, $a_{31} = a_{3j}^T A^T$, ..., $a_{n1} = a_{nj}^T A^T$
 - Inverse
 - $A^{-1} = D^{-1} A^{-1} I$
 - $A^{-1} = D^{-1} A^{-1} \cdot (D^{-1})^T = (A^{-1})^T$; $D = \frac{1}{\det A} A^T$
 - quadratische $A^{-1} = D^{-1} A^T$
 - Eigen
 - $\lambda v = Av = \lambda v \Leftrightarrow (\lambda I - A)v = 0$
 - $p(\lambda) = \det(\lambda I - A) = 0$ (charakterist. Polynom)
 - durch $\lambda_1, \lambda_2, \dots, \lambda_n$ multipliziertes Eigenvektor
 - zugehörig: $\{v_i \mid v_i \in \lambda_i I - A\}$ Subraum
 - Symmetrisch: $A = A^T$
 - orthogonal: $A^T A = A A^T = I$
 - diagonal: $A^T A = A A^T$ (reell)
 - orthogonal-hermitische: $(AB)^T = B^T A^T$ (komplex)
 - singuläre Werte: $\lambda = \sqrt{\lambda_1^2 + \lambda_2^2 + \dots + \lambda_n^2}$
 - Singulärer Wert (SVD)
 $\mathbf{A} = U \Sigma V^T$
 $\Sigma = \begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_n \end{pmatrix}$
 - Norm
 - $\|G\| = 0$
 - $\|G(A)\| = \|\det G(A)\|$
 - $\|G(A+B)\| \leq \|G(A)\| + \|G(B)\|$ "Subadditivität"
 - $\|G(A)\| \leq \|G(A)\|_{\text{operator}}$
 - Frobeniusnorm
 $\|A\|_{\text{Frob}} = \sqrt{\text{Tr}(A^T A)} = \sqrt{\langle \text{Tr}(A^2), 1 \rangle}$
 $= \sqrt{\text{Tr}(A^H A)}$ wenn A herm.
 $\|A\|_{\text{Frob}} = \sqrt{\sum_{i,j} |\alpha_{ij}|^2}$
 - Quadrat der Frobeniusnorm
 - Operatormodul
 - $\|A\|_{\text{operator}} = \max_{\|x\|=1} \frac{\|Ax\|}{\|x\|}$ oder $\|A\|_{\text{operator}} = \sqrt{\lambda_{\text{max}}(A^T A)}$
 - $\mu(A) \Leftrightarrow$ largest column norm
 - $\mu(A) \Leftrightarrow$ largest row norm
 - $\mu(A) \Leftrightarrow \sqrt{\lambda_{\text{max}}(A^T A)}$
 - Matrix 2
 - Orthogonale Basis (fundamental orthogonal)
 - $\text{proj}_{\mathbf{b}} = \frac{\mathbf{b}^T \mathbf{b}}{\|\mathbf{b}\|^2} \cdot \mathbf{b}$
 - Gram-Schmidt: \rightarrow lin. unabh., l.h.s. orthogonal
 - lin. Abh., l.h.s. nicht
 - \rightarrow L für QR-Faktorisierung
 - lin. Abh., parallel miteinander, linear unabh.
 - Kernel basis
 - length dim in \mathbb{C}^n : $K = X^T X$ kernel matrix
 - min $L(X^T w, y) + \lambda \|w\|^2$
 - solution in span of X_1, \dots, X_m

- kernel basis
 - rank-rank $\Phi(\mathbf{z})$
 - $K_{\mathbf{z}}^T K(\mathbf{z}, \mathbf{z}_0) = \Phi(\mathbf{z})^T \Phi(\mathbf{z}_0)$
 - kernel field $K(\mathbf{x}, \mathbf{z}) = \Phi(\mathbf{x})^T \Phi(\mathbf{z})$
 - ex. product $(1 + x^2)^{-1}$
 - goal: pretty $(1 + x^2)^{-1}$
 $\Phi(\mathbf{x}) = \text{matrix} \Phi(\mathbf{x})$
 - ex. gamma $K(\mathbf{x}, \mathbf{z}) = \exp\left(-\frac{\|\mathbf{x} - \mathbf{z}\|_2^2}{2\sigma^2}\right)$
 matrix Mixture
 superposition $C = \sum_{i=1}^m \bar{C}_i (\mathbf{x}^{(i)} - \mathbf{z}) (\mathbf{x}^{(i)} - \mathbf{z})^T$
 $C = \frac{1}{n} \sum_{i=1}^n \bar{C}_i \mathbf{x}^{(i)} \mathbf{x}^{(i)T}$
 - $\mathbf{w}^T C \mathbf{w}$ = variance along line $\Phi(\mathbf{C} \mathbf{w})$
 Matrix ratio $\frac{\partial \Phi(\mathbf{x})}{\partial \mathbf{x}_j}$ aka $\Phi'(\mathbf{x})$
 $H_{ij} = \frac{\partial^2 \Phi(\mathbf{x})}{\partial \mathbf{x}_i \partial \mathbf{x}_j}$ symmetric!
 gradient $\nabla \Phi(\mathbf{x}) = \Phi'(\mathbf{x}) \mathbf{x}$
 - Spectral Theorem $\Phi(\mathbf{x}) = Q \Lambda Q^T$
 - eigenvalues $\Rightarrow \Lambda = Q \Lambda Q^T$
 $= \frac{1}{2} \lambda \mathbf{x} \mathbf{x}^T$
 Amount $\frac{\mathbf{x}^T \Lambda \mathbf{x}}{\mathbf{x}^T \mathbf{x}}$ = variance
 Rayleigh quotient
 - matrix gain $\frac{\|\mathbf{b}\|_2^2}{\|\mathbf{A}\mathbf{b}\|_2^2}$
 - L2 spectral norm $\sqrt{\lambda_{\max}(\mathbf{A}^T \mathbf{A})}$
 - diag \mathbf{a}_{ii}
 - PFO $\Rightarrow \mathbf{A}^T \mathbf{A} \geq 0, \Lambda \geq 0$
 - PFO $\Rightarrow \mathbf{A}^T \mathbf{A} > 0, \Lambda > 0$
 - IFA inviolable
 $\Lambda^T \Lambda \geq 0 \Leftrightarrow \Lambda \Lambda^T \geq 0$
 $\Lambda^T \Lambda \geq 0 \text{ iff } \Lambda \text{ full column}$
 $\Lambda^T \Lambda > 0 \text{ iff } \Lambda \text{ full rank}$
 - Matrix gain R
 $R = \Lambda^T \Lambda \Rightarrow R = \Lambda \Lambda^T$
 $\Lambda = Q \Lambda Q^T$
 $R = Q \Lambda^2 Q^T$
 - Ellipsoid
 - $E = \{(\mathbf{x} - \mathbf{c})^T \mathbf{P}^{-1} (\mathbf{x} - \mathbf{c})\}, \mathbf{P} > 0$
 - \mathbf{c} : center, length $\sqrt{\mathbf{c}^T \mathbf{P} \mathbf{c}}$
 - Cholesky Decomp $\mathbf{P}^{-1} = \Lambda^T \Lambda$
 $\mathbf{c} = (\mathbf{E}) / \|(\mathbf{E})\|_F \leq \frac{1}{2} \mathbf{c}^T \mathbf{c}$
 - set of PFO is cone S^n
 - compact convex
 - Schur Complement
 $M = \begin{pmatrix} A & X \\ X^T & B \end{pmatrix}, A, B \text{ symmetric}$
 $B > 0$
 $\Rightarrow A - X B^{-1} X^T$
 $\Rightarrow M \geq 0 \Leftrightarrow S \geq 0$
 width ≈ 100
 - SVD
 $\mathbf{A} = \mathbf{U} \tilde{\mathbf{S}} \mathbf{V}^T = \sum_{i=1}^r \sigma_i \mathbf{u}_i \mathbf{v}_i^T$
 - r rank(), $\tilde{\mathbf{S}}$: singular values $\tilde{\mathbf{S}} \geq 0$
 $- \tilde{\mathbf{S}}_i^2 = \mathbf{A}^T (\mathbf{A} \mathbf{A}^T) = \mathbf{A}^T (\mathbf{A} \mathbf{A}^T)^T$
 $- \mathbf{A}(\mathbf{A}^T)^T = \text{last } n-r \text{ columns of } \mathbf{V}$
 $- \mathbf{R}(\mathbf{A}) = \text{first } r \text{ columns of } \mathbf{U}$
 $\|\mathbf{A} \mathbf{U} \mathbf{V}^T\|^2 = \sum_{i=1}^r \tilde{\sigma}_i^2$
 $\|\mathbf{A} \mathbf{U} \mathbf{V}^T\|^2 = \tilde{\mathbf{S}}^2$
 - multivariate normal $\mathcal{N}(\mathbf{0}, \Sigma) \in \mathbb{R}^{d \times d}$
 - trace: cyclic involution
 - condition number $K(\mathbf{A}) = \frac{\sigma_1}{\sigma_n} = \|\mathbf{A} \mathbf{A}^T\|_2 / \|\mathbf{A}^T \mathbf{A}\|_2$
 $\# \rightarrow \text{close to singular}$
 - condition number $\kappa(\mathbf{A}) = \frac{\sigma_1}{\sigma_n} = \|\mathbf{A} \mathbf{A}^T\|_2 / \|\mathbf{A}^T \mathbf{A}\|_2$
 - low rank approx
 $\min_{\mathbf{B}} \|\mathbf{A} - \mathbf{B}\|_F^2 \Rightarrow$ first k of SVD!
 - Frobenius norm $\|\mathbf{A}\|_F = \sqrt{\sum_{i,j} a_{ij}^2}$
 - error $\epsilon_A = 1 - \eta_A$
 - rank deficiency due to parallel lines!
 - PCA is SVD of centered matrix
 $\mathbf{X} \mathbf{X}^T \text{ symmetric, rank } 2 \leq (\mathbf{X} \mathbf{X}^T)^{-1} \leq$
 - Gram-Schmidt orthogonalization
 $\mathbf{u}_1 = \frac{1}{\|\mathbf{x}_1\|} \mathbf{x}_1, \mathbf{u}_2 = \frac{1}{\|\mathbf{x}_2 - \mathbf{u}_1\|} (\mathbf{x}_2 - \mathbf{u}_1)$
 - orthogonal PLS did $\mathbf{Y}(\mathbf{H} \mathbf{H}^T)^{-1} \mathbf{H} \mathbf{H}^T \mathbf{y}$
 - John $\mathbb{E} = \text{cov}(\mathbf{0}, \mathbf{E} \mathbf{y}) = \mathbf{U} \mathbf{U}^T \mathbf{y}^T$
 - Threshold δ
 - Non-negative matrix factorization (NMF), $\mathbf{L} \geq 0, \mathbf{R} \geq 0$
 - nonnegative

- Linear Equations

 - Ax = y
 - Vandermonde poly solve ($\lambda_{ij} = x_i^{j-1}$)
 - gda, ill. regularization
$$S = \{x \in \mathbb{R}^n | Ax = b\}$$
 - Ax = y, solution set A
 - unique soln if $A^{-1} \neq 0$
 - over-determined $m > n$
 - under-determined $m < n$
 - orthonormal
 - square min ||Ax - b||²
 - Normal equations
 - Solves LSE
 - Ax = y, Ax = b
 - $\frac{1}{2} \|x\|^2$
 - Solve w/ QR
 - back-substitution is singular
 - Least Squares + Variance
 - LS fits Ax = y
 - $\min \|Ax - b\|^2$
 - $\rightarrow x^* = (A^T A)^{-1} A^T b$ (closed form)
 - sub. into $\min ||Ax - b||^2$
 - under-determined
 - $x^* = A^T (AA^T)^{-1} y$
 - OLS w/ QR
 - $b = (R^T Q)^T x^* = R^{-1} Q^T$
 - LS w/ QR
 - $\min \|Ax - b\|^2$ s.t. $Cx = d$
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|Cx - d\|^2$
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|C^T(x - d)\|^2$
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|C^T x - C^T d\|^2$
 - weighted LS
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|w^T x - y\|^2$
 - regularized LS
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|x\|^2$
 - $\rightarrow \min \|Ax - b\|^2 + \lambda \|x\|^2$ (minimization w/ L1)

- Linear Programs

 - Half-space $a^T x + b \leq a^T x^*$
 - Polyhedron $a^T x \leq b$:
 - column (vertices)
 - vertices at boundaries - LP Standard form: $\min c^T x + d$
 - $p^* = \min c^T x + d$
 - a. $Ax \leq b$
 - $Ax \leq b$
 - "equality form"
 - b. $Ax = b$
 - LP dual problem
 - $\text{optimal} \ L(\bar{x}, \bar{y}) = \bar{c}^T \bar{x} + \bar{d}$
 - simplex method
 - interior point methods
 - KKT conditions
 - KKT
 - calculate w/ LP!!!
 - Reduction
 - $\min z \rightarrow \max -z$

- Convex Quadratic Programs

$$P(x) = \frac{1}{2} x^T H x + c^T x + d$$

$$H = \frac{1}{2} (H^T + H)$$

$$G = \frac{1}{2} (H^T H)^{-1}$$
 - convex H \Rightarrow H ≥ 0
 - QP
 - $\min P(x) \rightarrow$
 - $\min Ax = b$
 - $\min ||Ax - b||^2 + \lambda x^T x$
 - $\min ||Ax - b||^2 + \lambda ||x||_1$
 - $\min ||Ax - b||^2 + \lambda ||x||_2$
 - $\min ||Ax - b||^2 + \lambda ||x||_3$
 - $\min ||Ax - b||^2 + \lambda ||x||_\infty$
 - $\min ||Ax - b||^2 + \lambda ||x||_F$
 - $\min ||Ax - b||^2 + \lambda ||x||_k$
 - $\min ||Ax - b||^2 + \lambda ||x||_p$
 - $\min ||Ax - b||^2 + \lambda ||x||_q$
 - $\min ||Ax - b||^2 + \lambda ||x||_r$
 - $\min ||Ax - b||^2 + \lambda ||x||_s$
 - $\min ||Ax - b||^2 + \lambda ||x||_t$
 - $\min ||Ax - b||^2 + \lambda ||x||_u$
 - $\min ||Ax - b||^2 + \lambda ||x||_v$
 - $\min ||Ax - b||^2 + \lambda ||x||_w$
 - $\min ||Ax - b||^2 + \lambda ||x||_x$
 - $\min ||Ax - b||^2 + \lambda ||x||_y$
 - $\min ||Ax - b||^2 + \lambda ||x||_z$

- Second Order Cone Program

 - equivalent to LP, QP
 - Second Order Cone (SOC)
 - $L^{(1)} = \{x \in \mathbb{R}^n : \|Lx\|_2 \leq 1\}$
 - extended SOC: $B^{(1,2)}$
 - $L^{(2)} = \{x \in \mathbb{R}^n : \|Lx\|_2 \leq 1\}$
 - $K^{(2)} = \{(x, y) \in \mathbb{R}^n \times \mathbb{R}^m : \|Lx\|_2 \leq \|y\|_2, y \geq 0\}$
 - epigraph $\text{epi } f(x, \{y \geq 0\})$
 - hyperplane constraints
 - Standard SOC
 - $\|Bx\|_2 \leq C^T x + d$
 - QP \rightarrow SOC
 - $\min \|Qx\|_2 + c^T x$
 - $\min \|Qx\|_2 + c^T x + b$
 - $\min \|Qx\|_2 + c^T x + b + \lambda \|x\|_2$
 - QCQP \rightarrow SOC
 - $\min \|Qx\|_2 + c^T x$
 - $\min \|Qx\|_2 + c^T x + b$
 - $\min \|Qx\|_2 + c^T x + b + \lambda \|x\|_2$
 - $\min \|Qx\|_2 + c^T x + b + \lambda \|x\|_1$
 - $\min \|Qx\|_2 + c^T x + b + \lambda \|x\|_0$

- Robust Optimization

 - uncertainty set w/ ellipsoids
 - robust performance
 - constraint
 - $\min f(x), f(x) \leq 0$
 - $\text{if } f(x) = \text{"uncontrollable"}$
 - $\min \max_i f_i(x_i)$
 - $f_i(x_i) \leq 0$ constraint
 - add uncertainty w/ ellip.
 - single inequality w/ multiple ellipsoids
 - $\min f(x) \leq 0$
 - $\rightarrow \min \max_i f_i(x_i) \leq 0$
 - max $\min_i f_i(x_i) \leq 0$
 - $\rightarrow \frac{1}{n} \sum_i f_i(x_i) \leq 0$
 - ellipsoid $P(x) \leq 0$
 - $\rightarrow \min \max_i P_i(x_i) \leq 0$
 - sphere $\|x - \mu\|_2 \leq r$
 - $\rightarrow \min \max_i \|x - \mu_i\|_2 \leq r$
 - ellipsoid $P(x) \leq 0$
 - $\rightarrow \min \max_i P_i(x_i) \leq 0$
 - Convex LP
 - probability strategy > 0.99
 - Robust LS
 - $\min \|Ax - b\|_2$
 - $\min \max_i \|(A_i x - b_i)\|_2$
 - $\min \max_i \|(A_i x - b_i)\|_1$
 - robust quadratic L1

- Other

 - If $R(x) \geq 0$ combine SOC
 - return QP \rightarrow QCQP

- Convexity
 - set of points in \mathbb{R}^n , P
 - linear hull - all linear combinations
 - affine hull - contains 1 (affine)
 - smallest affine subset of P
 - convex hull - $A \geq 0$, $E = 1$
 - convex hull - set of all \sum
 - convex hull - $\sum \lambda_i x_i = \text{conv}(P)$
 - Convex - horizontal segment between x_1, x_2

$$x_1 + (1-\lambda)x_2 \in C, \lambda \in [0,1]$$
 - Convex - $\forall x \in C$
 - convex hull of $\{x\}$ is x
 - convex function $\nabla f(x) = 0$ outside domain
 - domain is convex
 - $f(x) + c(1-\lambda)y \leq f(x) + (1-\lambda)f(y)$
 - concave - f is convex
 - epigraph - plot above function y

$$f(x) \leq y \quad \forall x \in \text{dom } f$$
 - epif: $\{(x,y) : x \in \text{dom } f, f(x) \leq y\}$
 - sublevel set $S_y = \{x \in \mathbb{R}^n : f(x) \leq y\}$
 - convex $\Rightarrow S_y$ convex (and $\emptyset = S_\infty$)
 - $f(x) \leq E(x), x \in D \Rightarrow$ preimage function convex
 - First Order Condition
 - convex $\Leftrightarrow \nabla f(x) \text{ def.}, f'(x) \leq f(x)$
 - strict local min below by any hyperplane tangent
 - Second Order Condition
 - Hessian $D^2 f \in PSD \quad D^2 f \geq 0$
 - Positive Definite Maximizer

$$f(x) = \max_{\text{convex}} \quad \text{dom } f$$
 - max in SDP $\|Ax\|_2^2 = (x^T A x) \leq c$ convex
 - Convex Polytopes
 - LP, SLP, QCP, QCQP $\leq CP$
 - Standard Form

$$\begin{aligned} p &= \min_{x \in X} f_0(x) \\ &\quad s.t. \\ &\quad f_i(x) \leq 0 \quad i=1, \dots, m \\ &\quad g_j(x) = b_j \quad j=1, \dots, n \end{aligned}$$
 - implied $x \in \text{dom } f_0 \cap \{g_j = b_j\}$
 - implicit constraints
 - slack rows - all linear parts
 - regularizer ℓ_1
 - $p^* = \min_{x \in X} f_0(x) + \alpha \|\ell_1\|$
 - unrestricted $X \subseteq \mathbb{R}^n$
 - infinite X -arsity (by $\ell_1 \neq 0$)
 - limited $p^* = \infty$
 - parallel boundary in Slack form ($x \in C$)
 - $f(x) \leq c$ & $(x \in C) \Rightarrow$ convex
 - can remove ℓ_1 from convex
 - optimal set $X^* = \text{convex}$ always convex
 - convex \Rightarrow local opt = global opt
 - Transformations
 - monotone objective transformation
 - continuous and strictly increasing
 - $\lambda \mapsto \log \lambda$
 - slack variables - $g_j(x) = b_j - \ell_1$
 - equality \Rightarrow equality ($\ell_1 = 0 \leq \ell_2$)

$$\begin{aligned} p^* &= \min_{x \in X} g^* = -\ell_1 \\ b_0 &= \ell_1 \\ &\quad \ell_1 \geq 0 \text{ if} \\ &\quad \text{for nonnegative over } X \\ &\quad b < \text{nonnegative over } X \\ &\quad \text{Convex} \& f \& \text{strictly convex} \end{aligned}$$
 - Hidden Constraints
 - scalar ℓ_1 convex, products, sum \leq const

- Weak Duality
 - Optimizer Fixed x^*
 - $p^* = \min_x f(x)$
 - single parameter $\Rightarrow f(x) \geq 0$
 - $\geq f(x^*) = 0$
 - "primal"
 - Lagrangean \tilde{L}
 - $L(x, \lambda, v) = f(x) + \lambda L(x) + v^T b(x)$
 - λ at Vmax Lagrange multiplier or dual variable
 - v \rightarrow cost with domain
 - $\Rightarrow p^* = \min_{x, \lambda, v} L(x, \lambda, v)$
 - Minimizing inequality
 - $p^* = \min_{x, \lambda, v} L(x, \lambda, v) \geq \min_x \min_{\lambda, v} L(x, \lambda, v) = d^*$
 - Dual Duality $p^* \leq d^*$
 - $\frac{\text{gap}}{\text{dual}} = d^* - p^* \leq \frac{\text{gap}}{\text{primal}}$ constant \Leftrightarrow constant
 - dual variable range \Rightarrow feasible
 - Strong Duality
 - complementary
 - $p^* = \min_x f(x)$
 - constr $\Rightarrow f(x) \geq 0$
 - $\geq \min_x f(x) = p^*$ \Leftrightarrow feasible
 - $\Rightarrow L(x, \lambda, v) = f(x) + \lambda L(x) + v^T b(x) \geq p^*$
 - ($\gamma - \alpha$) - Relative Interior
 - constr $D = \{x \in \mathbb{R}^n : Ax \leq b, Fx = g\}$
 - rel int $D = \{x \in D : Ax < b, Fx < g\}$
 - Strong Feasible
 - $\exists x \in \text{rel int } D$ st. $Ax = b, Fx \leq g$
 - \Rightarrow Slater Condition for Constrained
 - Strong Feasible $\Rightarrow p^* = d^*$
 - barrier methods for interior
 - Primal-dual
 - w/ strong duality $p^* = d^*$ and x^*, v^*
 - $\geq p^* \geq d^*$
 - fail: $\max_x \min_{\lambda, v} L(x, \lambda, v)$ not solution in P^*
 - Fix error, then recompute feasibility
 - non-convex problem (like Lasso)
 - dual is violated (infeasible) $\min_{\lambda, v} p^*$ infeasible λ, v
 - old variables (Market val)
 - \Rightarrow Strong minimization Theorem
 - $\min_x f(x), \min_{\lambda, v} p^*$ bounded below
 - $\min_x f(x), \min_{\lambda, v} p^*$ converges to $x^* \in \mathbb{R}^n$
 - $\min_{\lambda, v} p^* \rightarrow \min_{\lambda, v} p^*$ converges to $\lambda^*, v^* \in \mathbb{R}^{m+n}$
 - $\min_x f(x) = \min_{\lambda, v} p^*$
 - $\min_x f(x)$ solvable \Leftrightarrow $\min_{\lambda, v} p^*$ solvable
 - Safe Feature Elimination (SAFE)
 - feature can remove infeasibility

- Algorithms
 - 1D, finite interval
 - Parody of gradient
 - From left or better
 - extend to available
 - 0D (Search for extreme)
 - update interval to available
 - (1D) bisection and $F'(x)$
 - $O(\log(1/\epsilon))$ for ϵ constant
 - $x^* = \text{endpt} \Rightarrow \text{explore end region}$
 - width goes
 - problem termination
 - split into every picture
 - branch conjugate F_1, F_2
 - $F_1(x) = \max_{\theta} x^\top \theta - F_2(\theta)$
 - $\theta = \text{center}$
 - Coordinate descent
 - good for "box" problems (Villars!)
 - also "gradient" $\nabla_x F(x)$ available
 - idea:
 - update 1 coordinate at time in 1D.
 - prove global min if strictly convex
 - "independent" coordinate
 - Gradient Stochastic method (CGM with stochastic minimization)
 - $X_t^{(k+1)} = \arg\min_{X_t^{(k+1)}} \frac{f(X_t^{(k)})}{t} + \frac{\lambda}{t} \|X_t^{(k)} - X_t^{(k)}\|_2^2$
 - when $g_t^* \in \mathbb{R}$, $g_t \in \mathbb{R}^d$, one by one
 - using $\mathbb{E}[g_t]$ for unknown
 - Admits no convex, only LIP w.r.t. X , strictly convex
 - \Rightarrow converge to global
 - Usually fails if non-convex, except from step size
 - Basic Gradient method
 - slow, convergence speed $X^{(k+1)} = X^{(k)} - \eta_k \nabla f_k(X^{(k)})$
 - Stochastic Gradient Descent (SGD)
 - main: $\mathbb{E}[f(X)] \leq f(X)$
 - update using each point or batch "minibatch"
 - $\mathbb{E}[f(X)] \leq L(\mathbb{E}[x]) X$
 - convex, but slow
 - Projected Gradient
 - $\min_X f(X)$ s.t. X is "simple" & can project onto
 - $\min_X f(X)$ s.t. $X \in \mathcal{X}$ part $\rightarrow X$
 - $X^{(k+1)} = \Pi_{\mathcal{X}}(X^{(k)} - \eta_k \nabla f(X^{(k)}))$
 - dual weight help
 - Newton's method for unconstrained
 - $\min_X f(X)$, then $\nabla^2 f(X), \nabla^2 f(X)^{-1} f(X)$
 - $X^{(k+1)} = \nabla^2 f(X^{(k)})^{-1} \nabla f(X^{(k)}) + X^{(k)}$
 - $\nabla^2 f(X) = \frac{\partial^2 f(X)}{\partial x_i \partial x_j} X^{(k+1)} = \frac{\nabla^2 f(X^{(k)})}{\nabla^2 f(X^{(k)})} X^{(k)}$
 - $H \square \text{Unit}$
 - Interior point for constraint prob
 - $\min_X f(X)$ s.t. $\mathcal{C}(X) \leq 0$
 - CVX: $\rightarrow \min_X f(X) - \eta_k \bar{F}(X)$
 - $\bar{F}(X) = \text{Convex combination}$
 - local convex "interior" to feasible

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Final

 - Principal Component Analysis
 - less complex, regression or classification
 - goal for
 - $\min L(\hat{y}_i^T w_i + b)$
 - with $w_i \in \mathbb{R}^{d+1}$ (bias)
 - Loss function
 - Squared: $L(z, \hat{z}) = (z - \hat{z})^2$
 - L1: $L(z, \hat{z}) = |z - \hat{z}|$, additive
 - hinge: $L(z, \hat{z}) = \max(0, 1 - z\hat{z})$, sum
 - Logarithmic: $L(z, \hat{z}) = -\log(z\hat{z})$, log margin
 - Linearized loss
 - $\min (X^T w + b)^2 + \lambda \|w\|^2 + \gamma \log(z\hat{z})$
 - $\Rightarrow \lambda \|w\|^2 + \gamma \log(z\hat{z})$ (additive)
 - $\min \frac{\lambda}{2} \|w\|^2 + \gamma \log(z\hat{z})$ (additive)
 - $\Rightarrow (\lambda X^T w + b)^2 + \lambda \|w\|^2 + \gamma \log(z\hat{z})$
 - Linear Classification rule: $\hat{y} = \text{sign}(w^T x + b)$
 - $\text{sign}(x) = 1$ if $x \geq 0$, else -1
 - Margins
 - Hypothesis: $H = \{w : w^T x = c\}$ (class boundary)
 - Margin: $\frac{1}{\|w\|}$ (distance from origin to boundary), $X^T w = c$
 - $\gamma(w^T x + b) \geq 1$
 - Decision: $\hat{y} = \text{sign}(w^T x + b)$
 - $L(w, b) = \frac{1}{n} \sum_{i=1}^n \max(1 - y_i(w^T x_i + b), 0)$
 - Soft margin: $L(w, b) = \frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \max(1 - y_i(w^T x_i + b), 0)$
 - Maximum likelihood
 - $L(w, b) = \prod_{i=1}^n \frac{1}{1 + e^{-y_i(w^T x_i + b)}}$
 - $\max_{w, b} L(w, b) = \sum_{i=1}^n \log(1 + e^{-y_i(w^T x_i + b)})$
 - Normalized: $L(w, b) = \sum_{i=1}^n \log(1 + e^{-y_i(w^T x_i + b)})$
 - Total loss: $L(w, b) = \sum_{i=1}^n \log(1 + e^{-y_i(w^T x_i + b)}) + \lambda \|w\|^2$
 - Decision rule: $\hat{y} = \text{sign}(w^T x + b)$
 - Underparameter Learning
 - as dimension d increases, training error decreases, validation error increases
 - PCA not robust to noise at all, ~~can't handle noise~~
 - Low rank matrix
 - $\min \|X - LR^T\|_F$ (rank penalty)
 - $\min \sum_{j=1}^r \|L_j^T(x_i, b^T r_j)\| + \epsilon_p(r) + \epsilon_q(r)$
 - Robust PCA
 - $X = LR^T + S$ (spam)
 - $\min \|X - LR^T\|_F$
 - NMF (Non-negative Matrix Factorization)
 - $X = L \cdot R$, $L \geq 0$, $R \geq 0$ (non-neg)
 - Sparse PCA
 - Matrix Completion
 - common with low ranks
 - $\min \|X - LR^T\|_F^2 + \gamma (\|L\|_F^2 + \|R\|_F^2)$
 - $L \geq X \geq R$
 - otherwise $L \leq R$
 - Sparse Convex Relaxation
 - finds local minima in graph
 - Gradient descent
 - $\min_{L, R} \frac{1}{2} \|X - LR^T\|_F^2 + \gamma \sum_{i,j} \mathbb{1}_{L_{ij} < 0}$
 - cardinality regularization
 - $\rho(\alpha) = \rho_1(\alpha) * \rho_2(\alpha)$ (additive)
 - $\text{eff}(\sum_{i,j} \alpha_{ij}) = 0$

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Final